

**A hierarchical FACE
behavior model for 3D
face tracking without
markers.**



I- Introduction

II- 3D reconstruction of the face

III- Dynamic modelisation of the face's muscles

IV- 3D tracking in image sequences



I- Introduction

Objectives:

Accurate Face tracking



Method analysis/synthesis loop



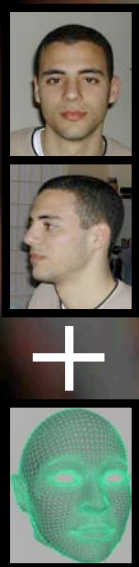
Accurate Face model, able to
create facial expressions



I- 3D reconstruction of the face

GLOBAL SCHEME

Data



Generic
Face

Calibration /
Reconstruction
loop

Camera
Calibration with
characteristic
points

3D points
Reconstruction

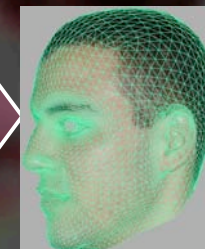
Deformation
Interpolation
by RBF

3D mesh
deformation by
RBF

Final
Deformation

Refinement
of the 3D
mesh by its
silhouettes

Result



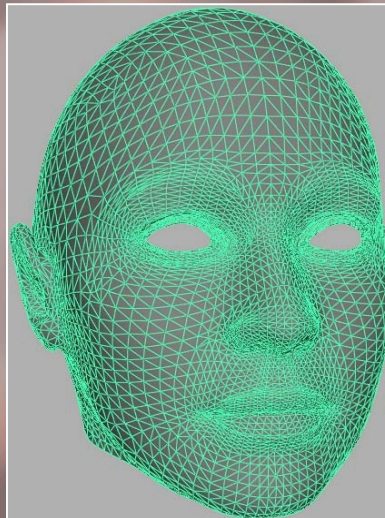
Specific
Face

Data

Input

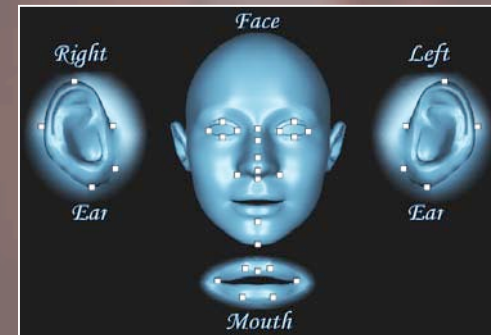


A priori knowledge



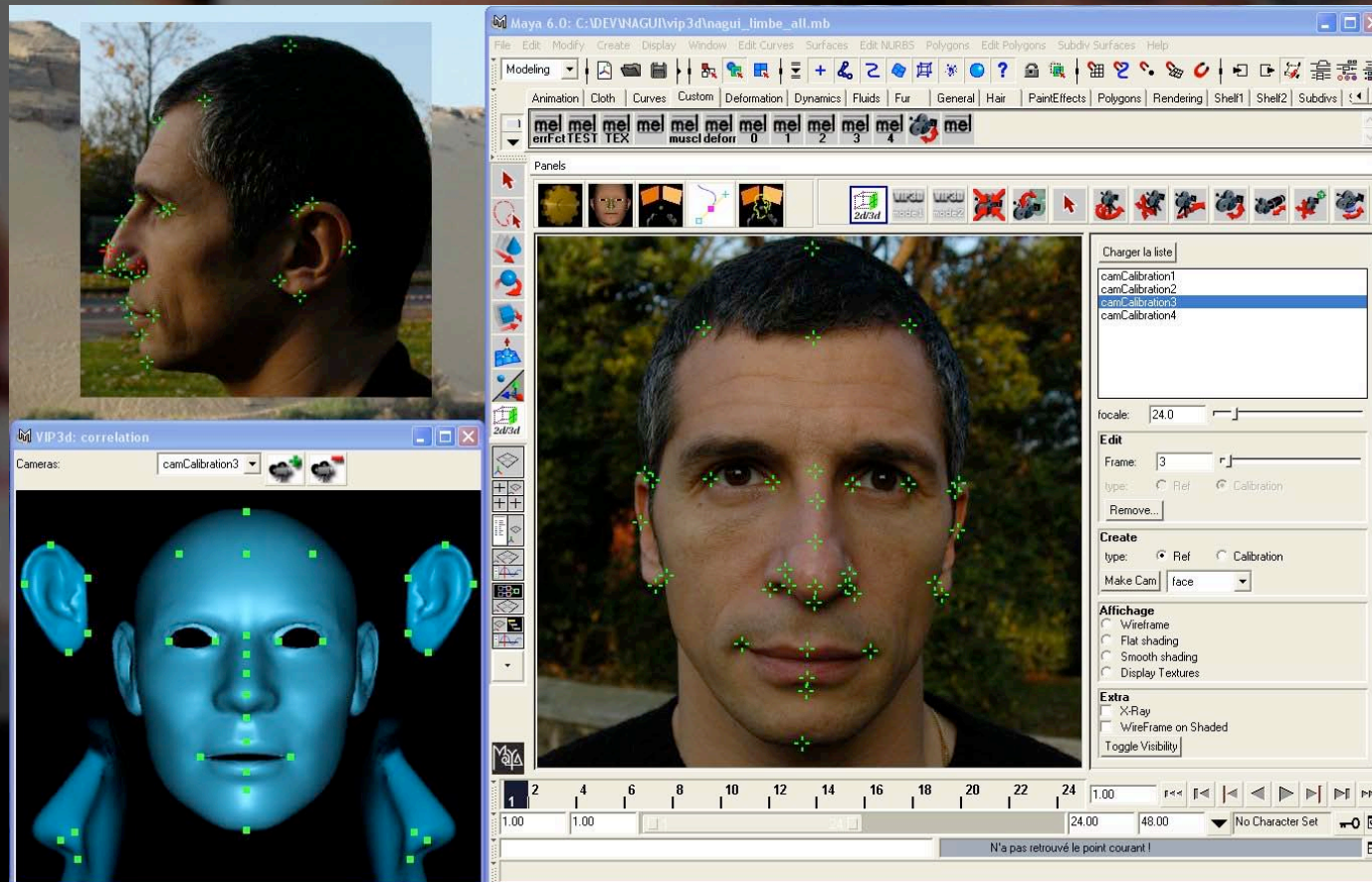
Generic model

+



38 characteristic points from MPEG-4 set

INTERACTIVE LABELING OF THE CHARACTERISTIC POINTS PROJECTIONS IN IMAGES



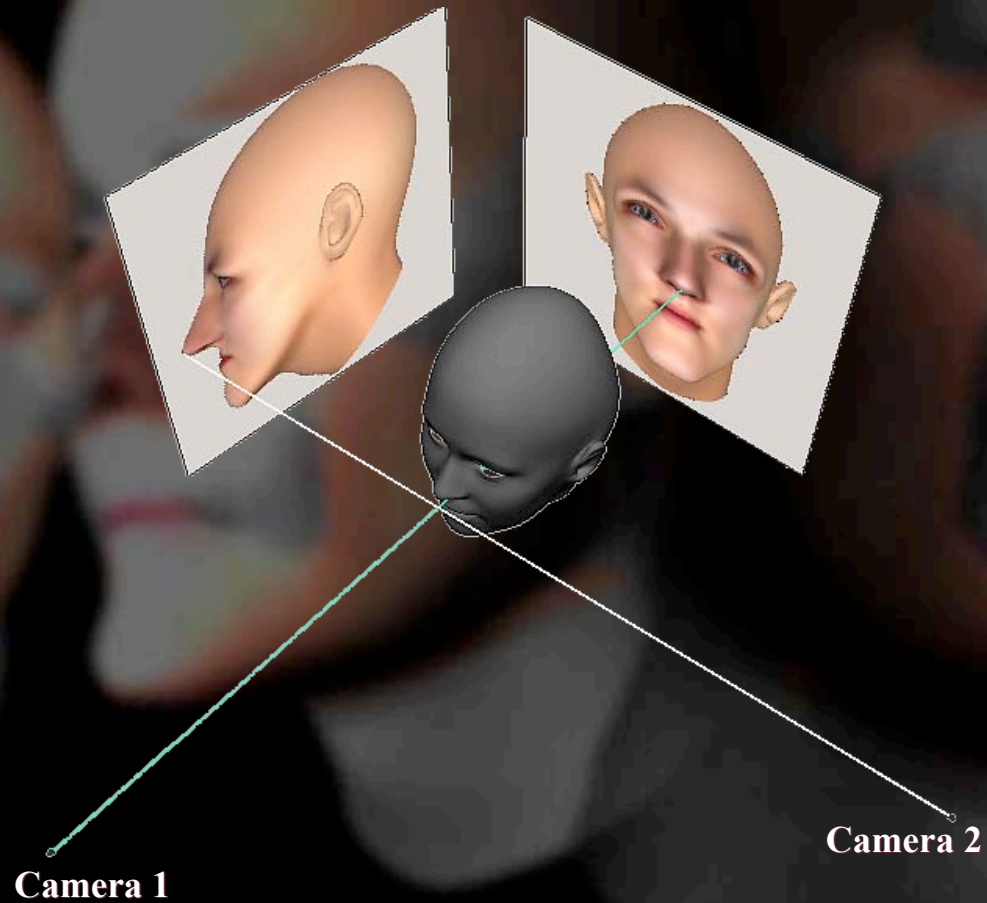
CAMERA CALIBRATION USING POSIT

A priori KNOWLEDGE:

**N 3D points and
their 2D projection,
where $N \geq 5$**

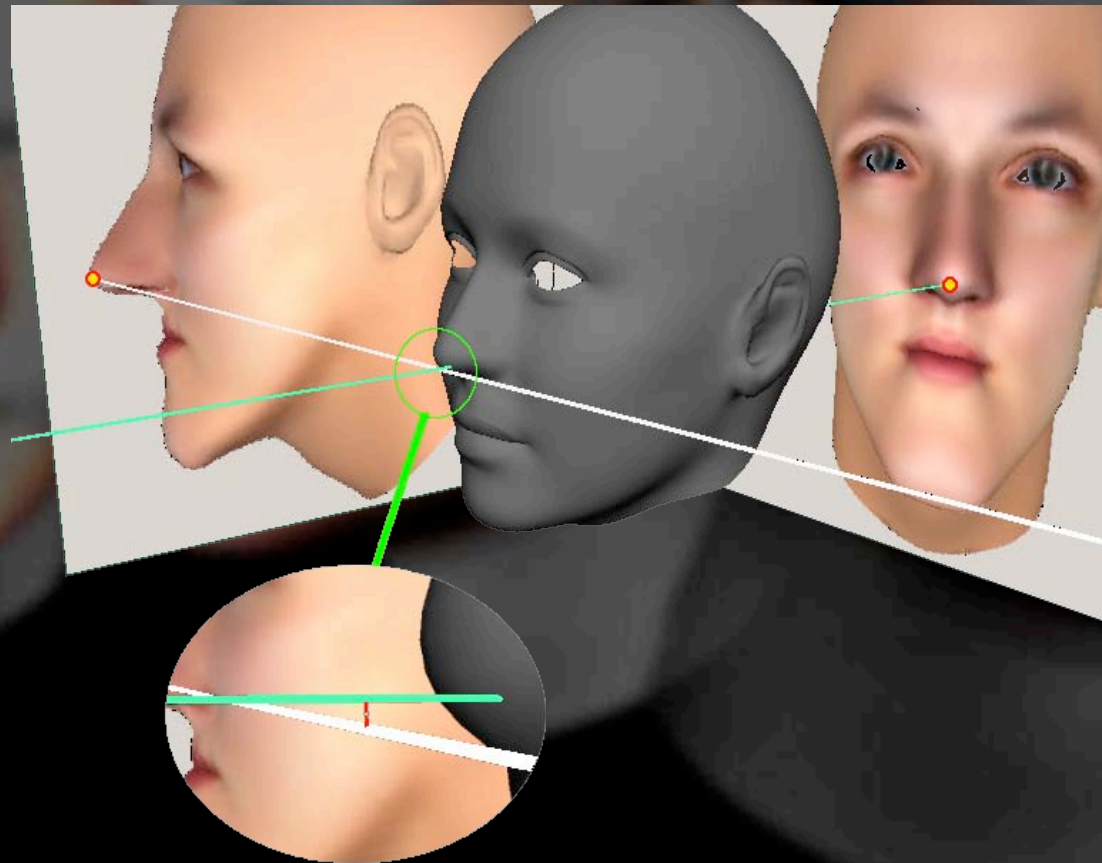
**Intrinsic parameters of
the cameras (focal length,
pixel ratio, optical centre)**

3D Reconstruction by simple stereo principle



3D Reconstruction by simple stereo principle

Calibration was not perfect



Calibration / Reconstruction loop

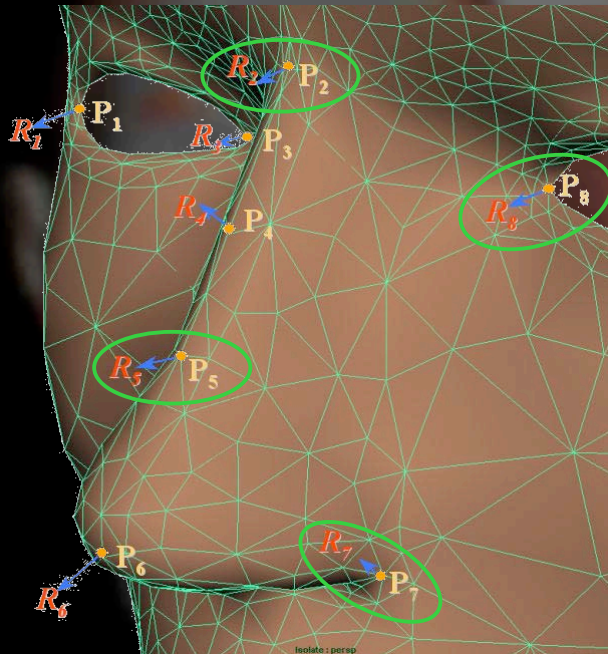
Calibration of
the cameras
using feature
points



3D
rebuilding of
features
points

Radial Basis Function

Given a set of deformation vectors



Basic idea:

1. Calculate the deformation at each feature point
2. Interpolate the deformations on the whole face

→ Radial Basis Function (RBF)

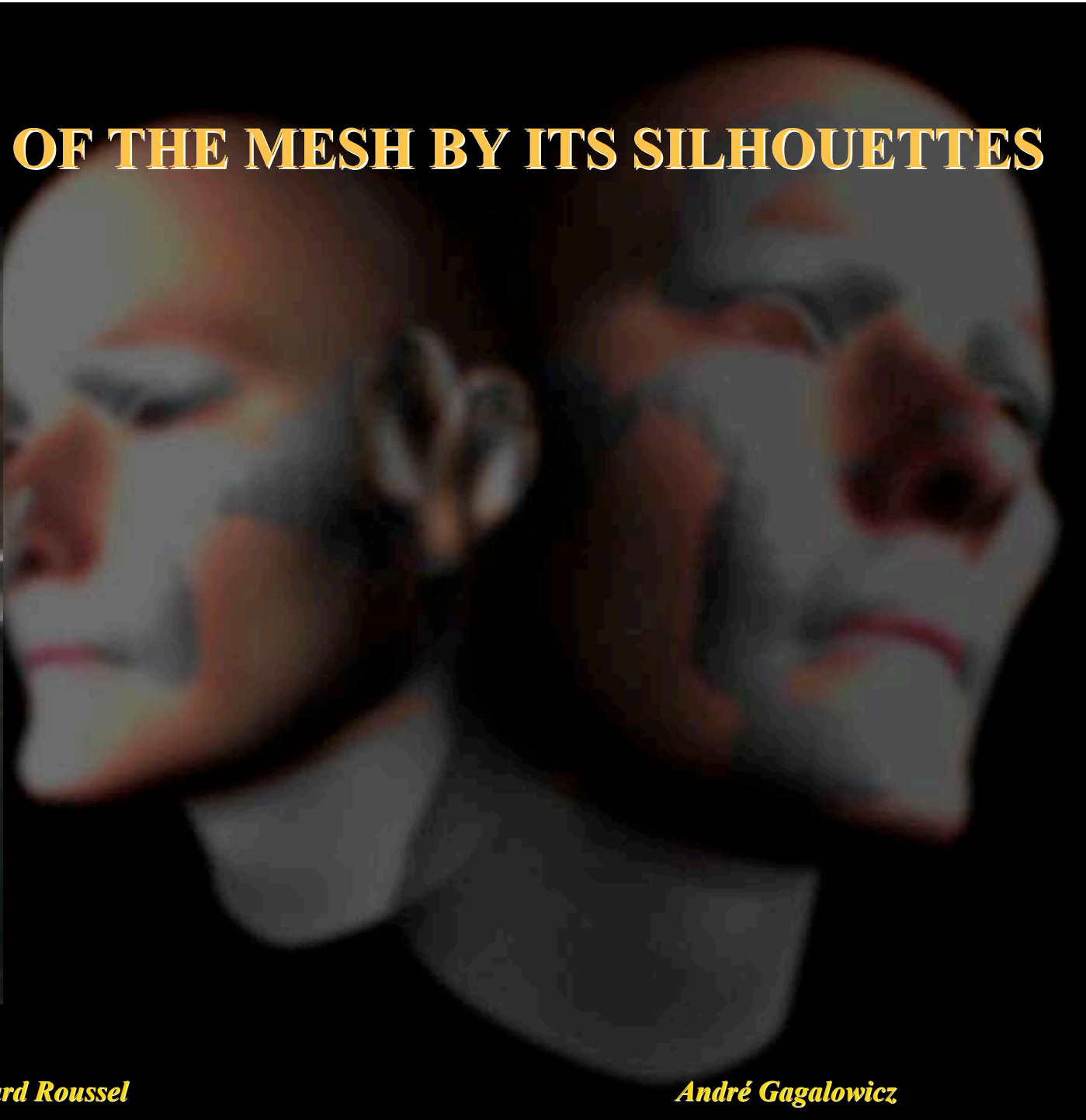
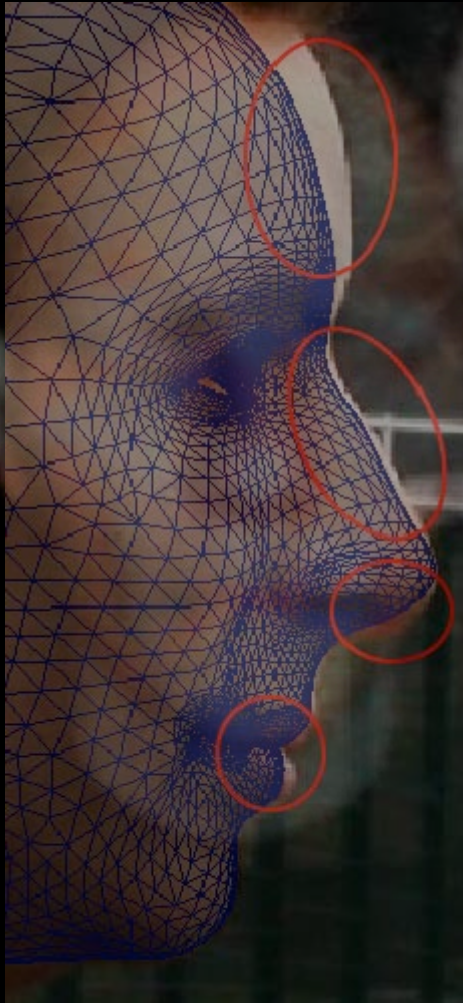
**Remaining
Problems:**



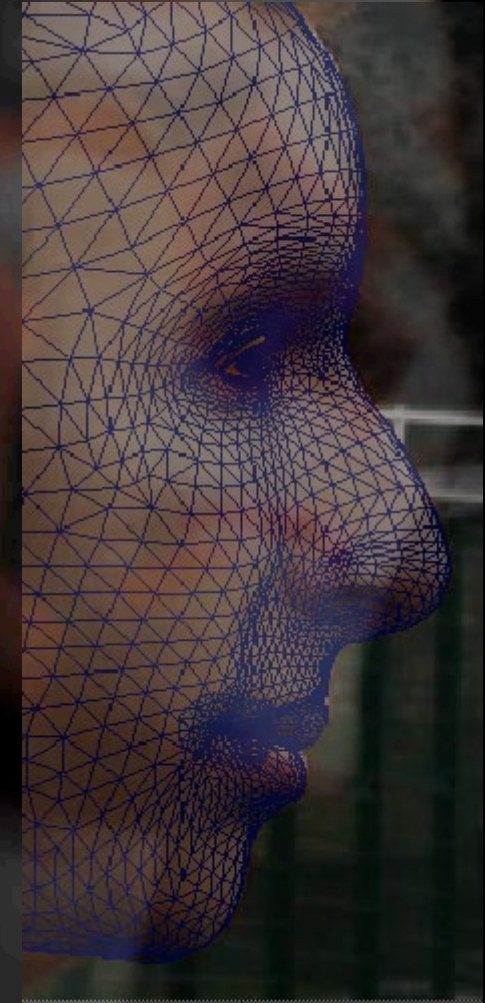
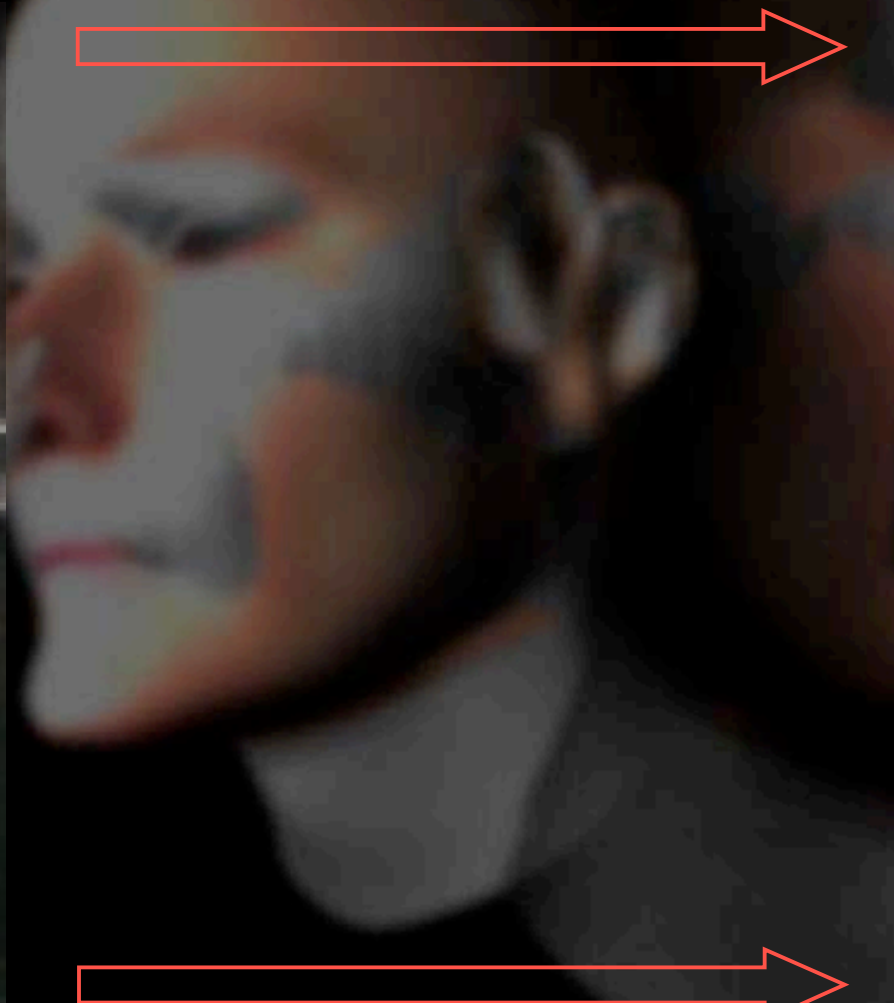
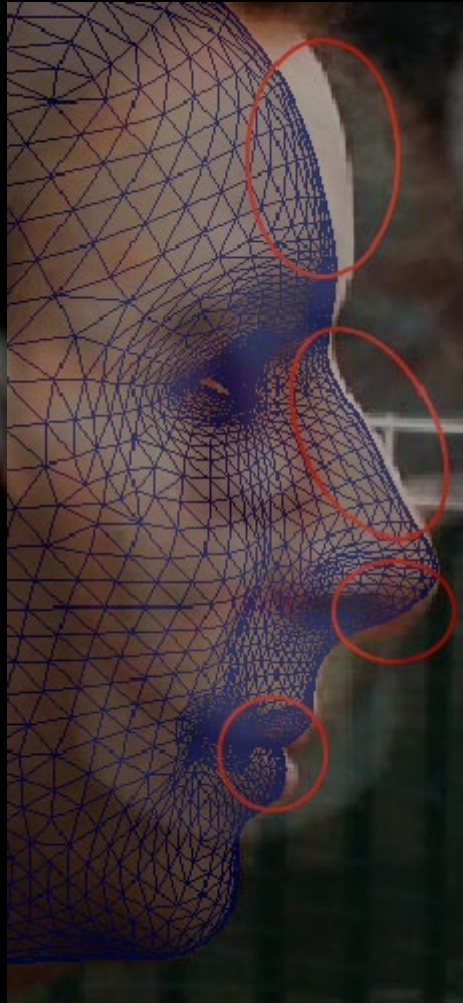
We want:



REFINEMENT OF THE MESH BY ITS SILHOUETTES



REFINEMENT OF THE MESH BY ITS SILHOUETTES



REFINEMENT OF THE MESH BY ITS SILHOUETTES

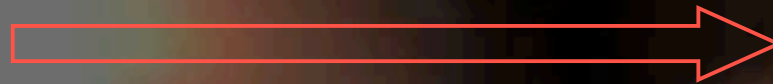
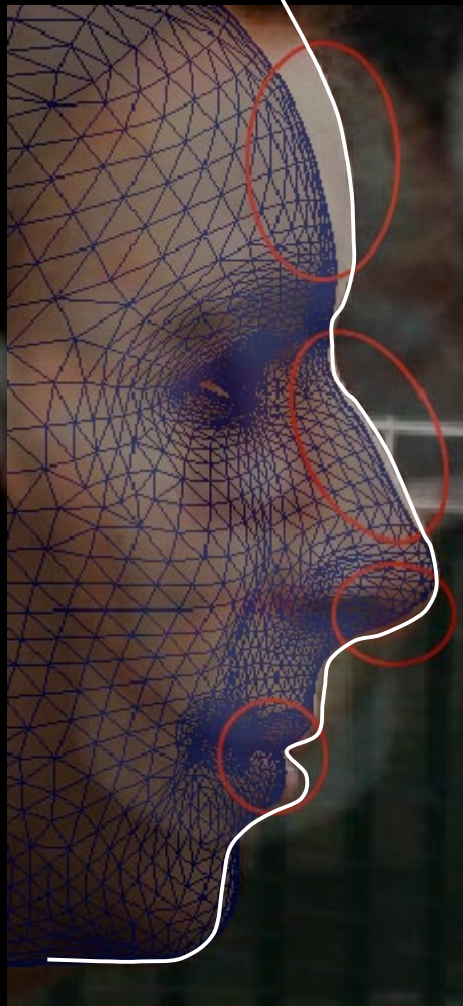
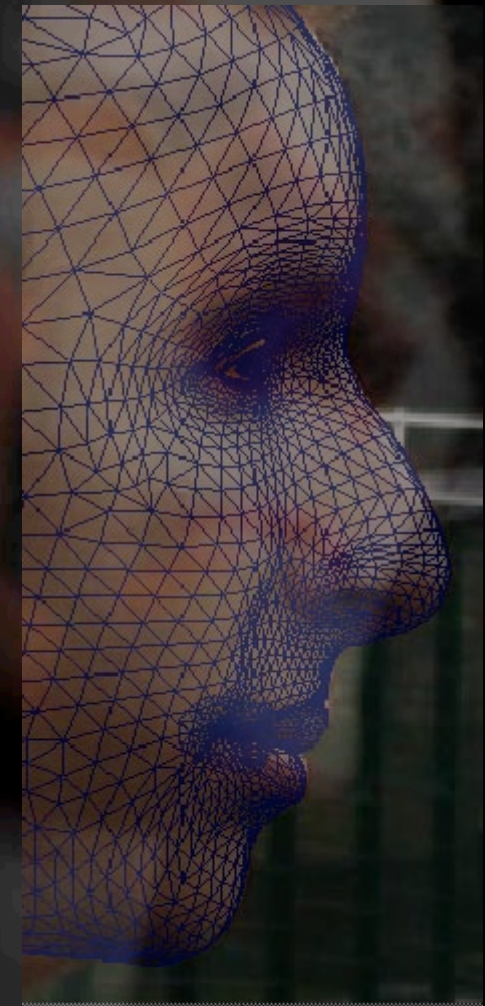


Image silhouette drawing





Caption:

- Control Point of the curve of Bézier
- + Following tangent, in the curve's direction
- Preceding tangent, in the curve's direction

REFINEMENT OF THE MESH BY ITS SILHOUETTES

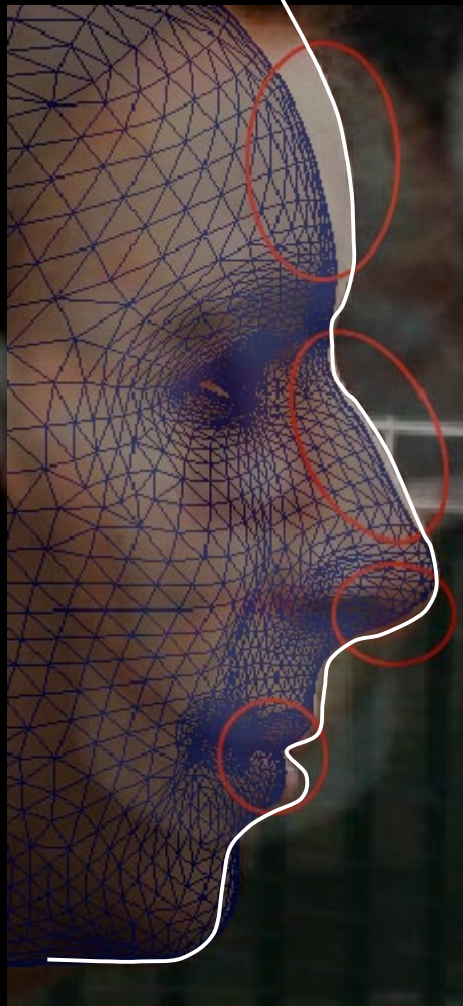
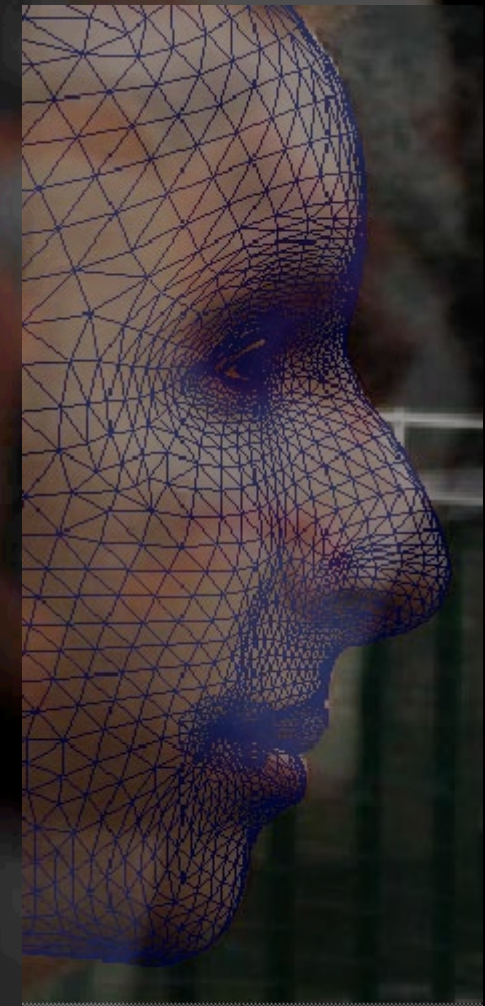
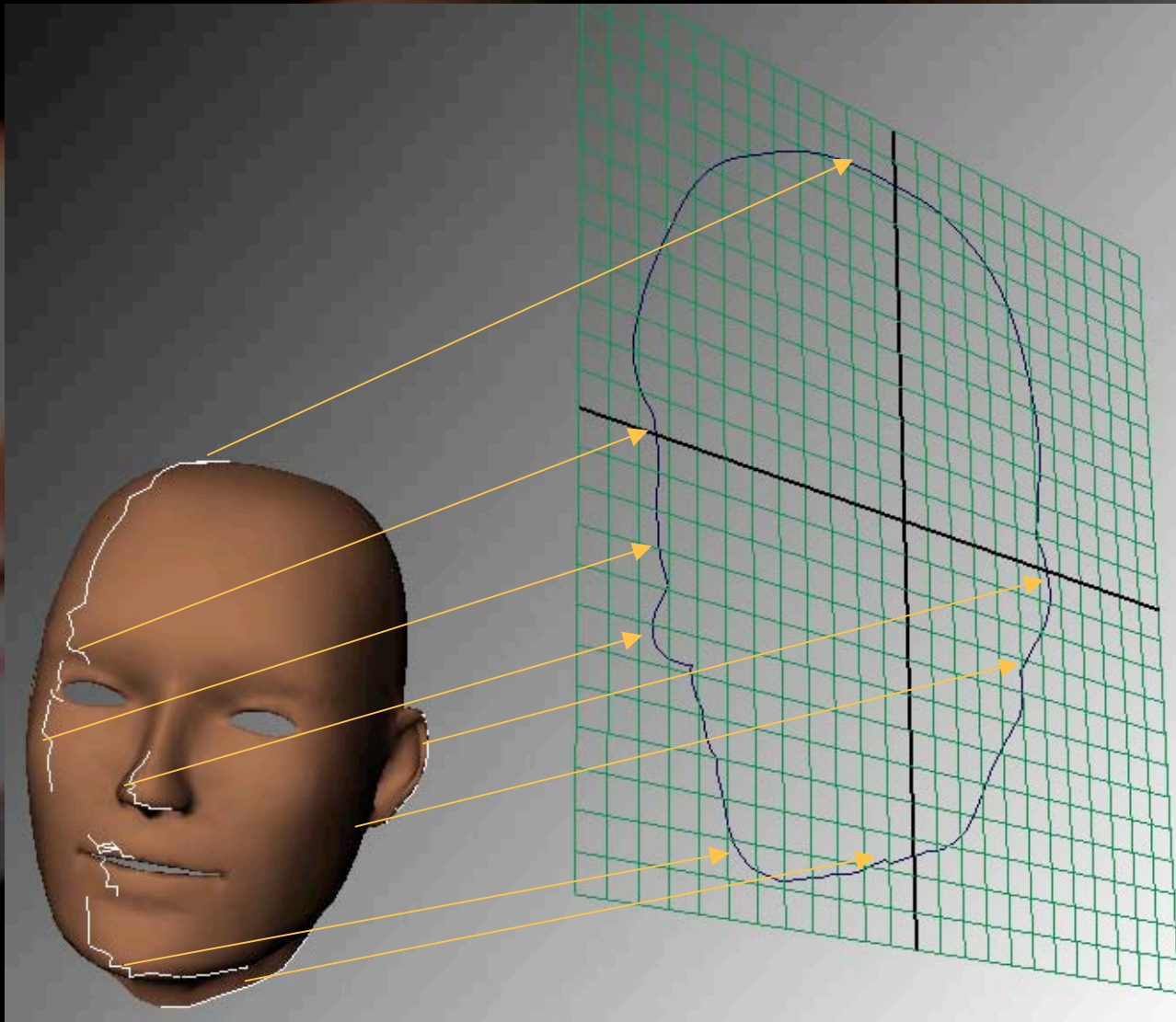


Image silhouette drawing

For each camera, computation of both
3D silhouette and its 2D projection





REFINEMENT OF THE MESH BY ITS SILHOUETTES

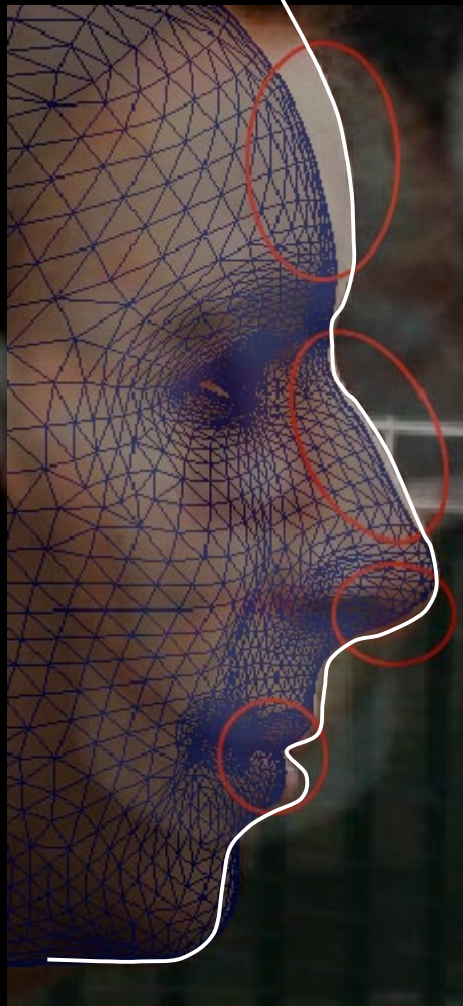
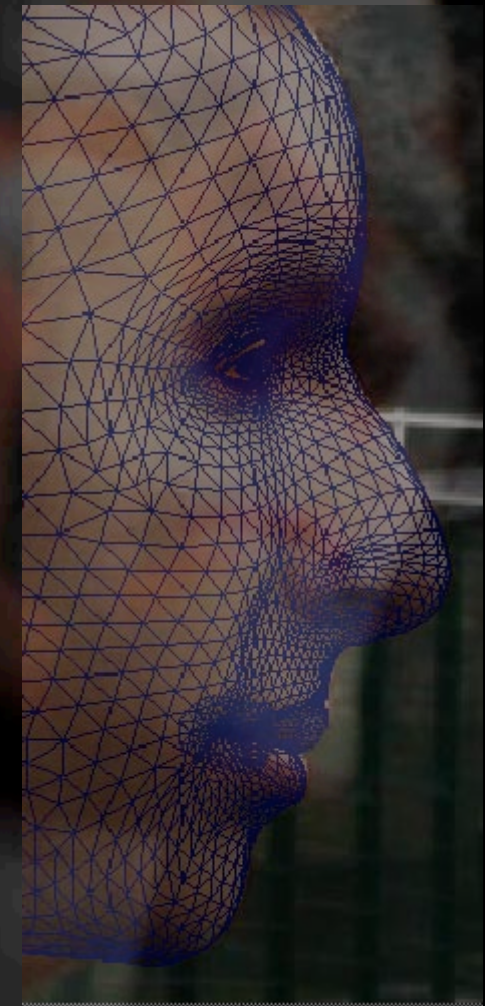
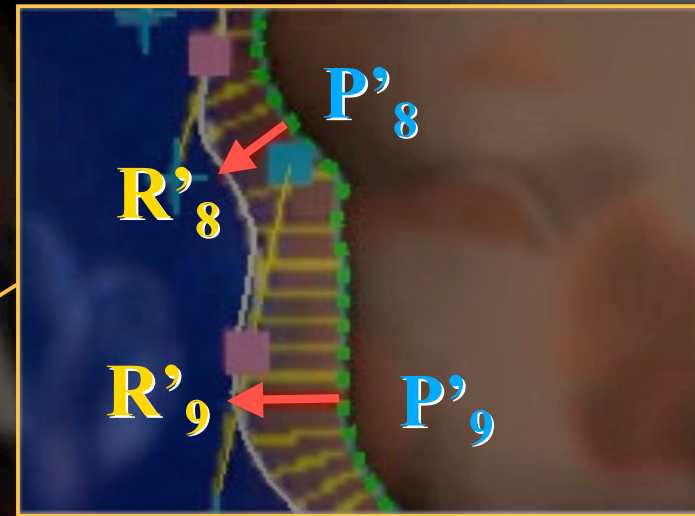
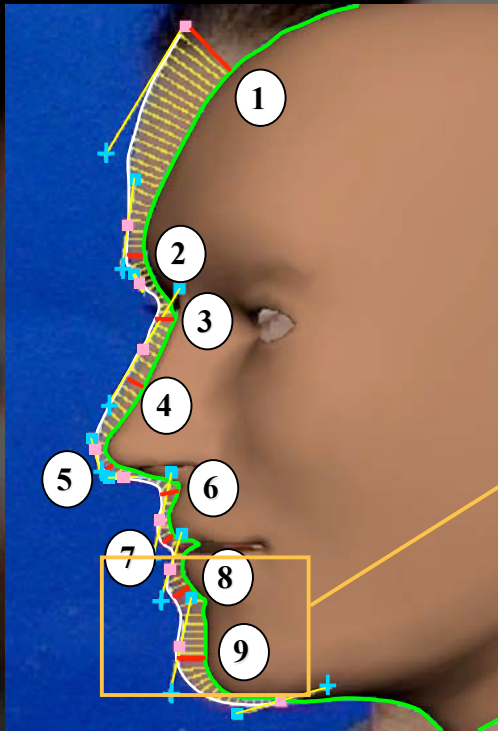


Image silhouette drawing

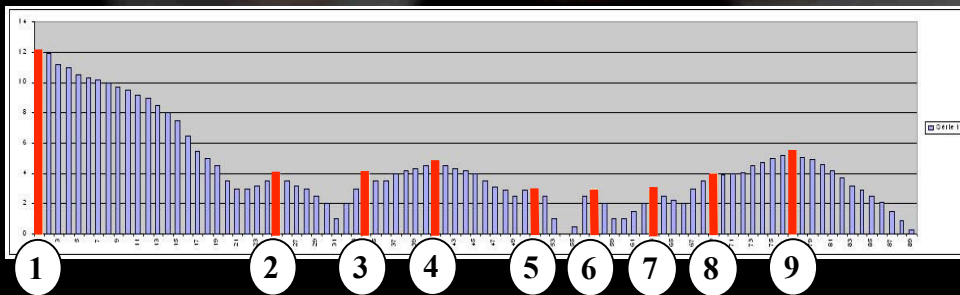
For each camera, computation of both
3D silhouette and its 2D projection

**Computation of the distances between
the projected and the image silhouettes.**





2D Deformation vectors



REFINEMENT OF THE MESH BY ITS SILHOUETTES

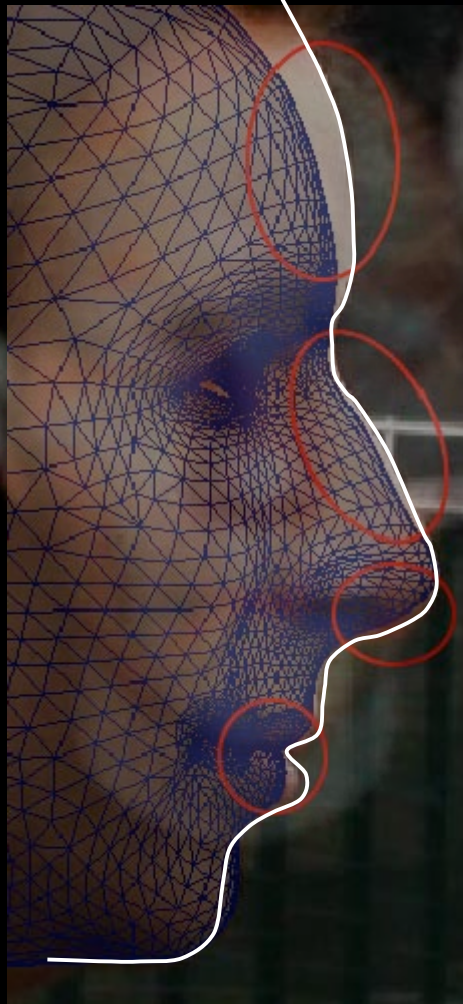
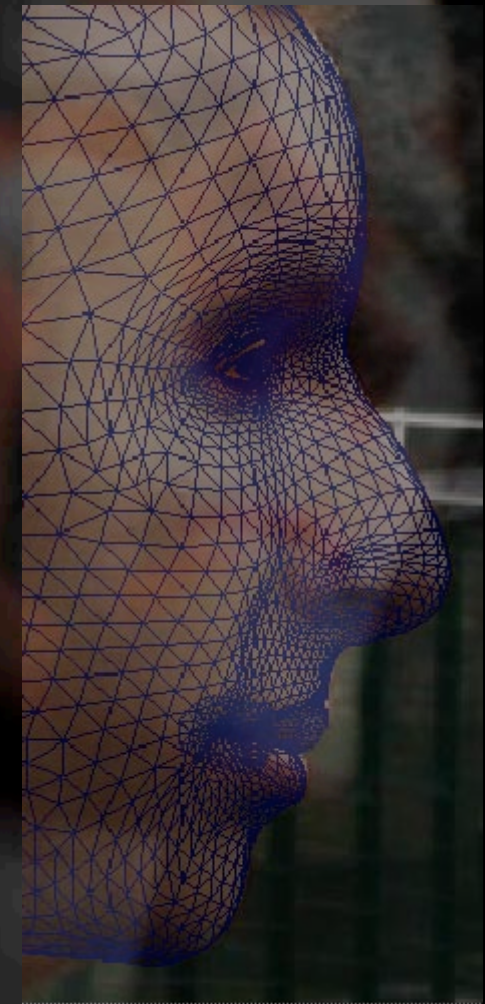


Image silhouette drawing

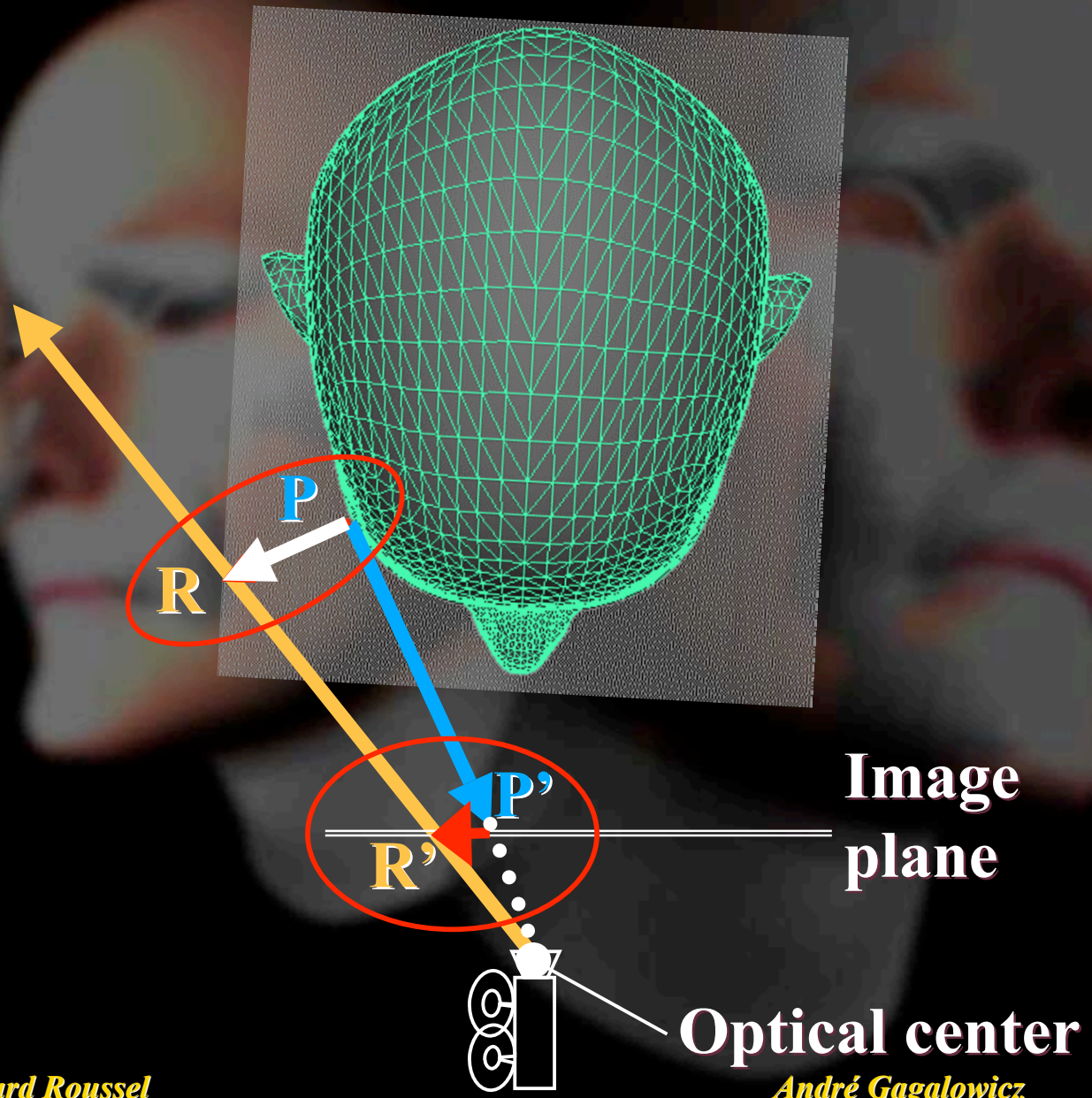
For each camera, computation of both
3D silhouette and its 2D projection

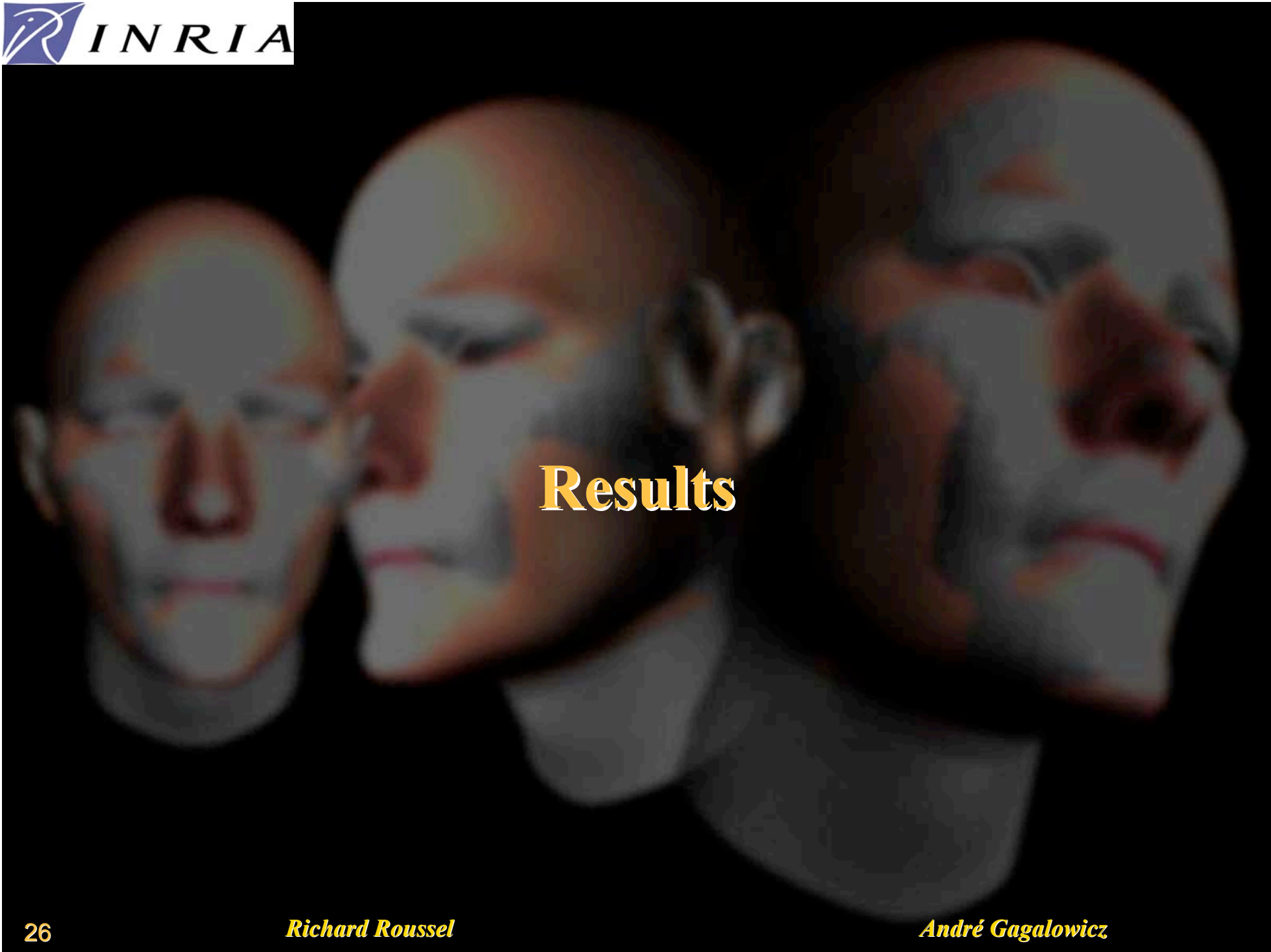
Computation of the distances between
the projected and the image silhouettes.

**Computation of the corresponding 3D
deformations**



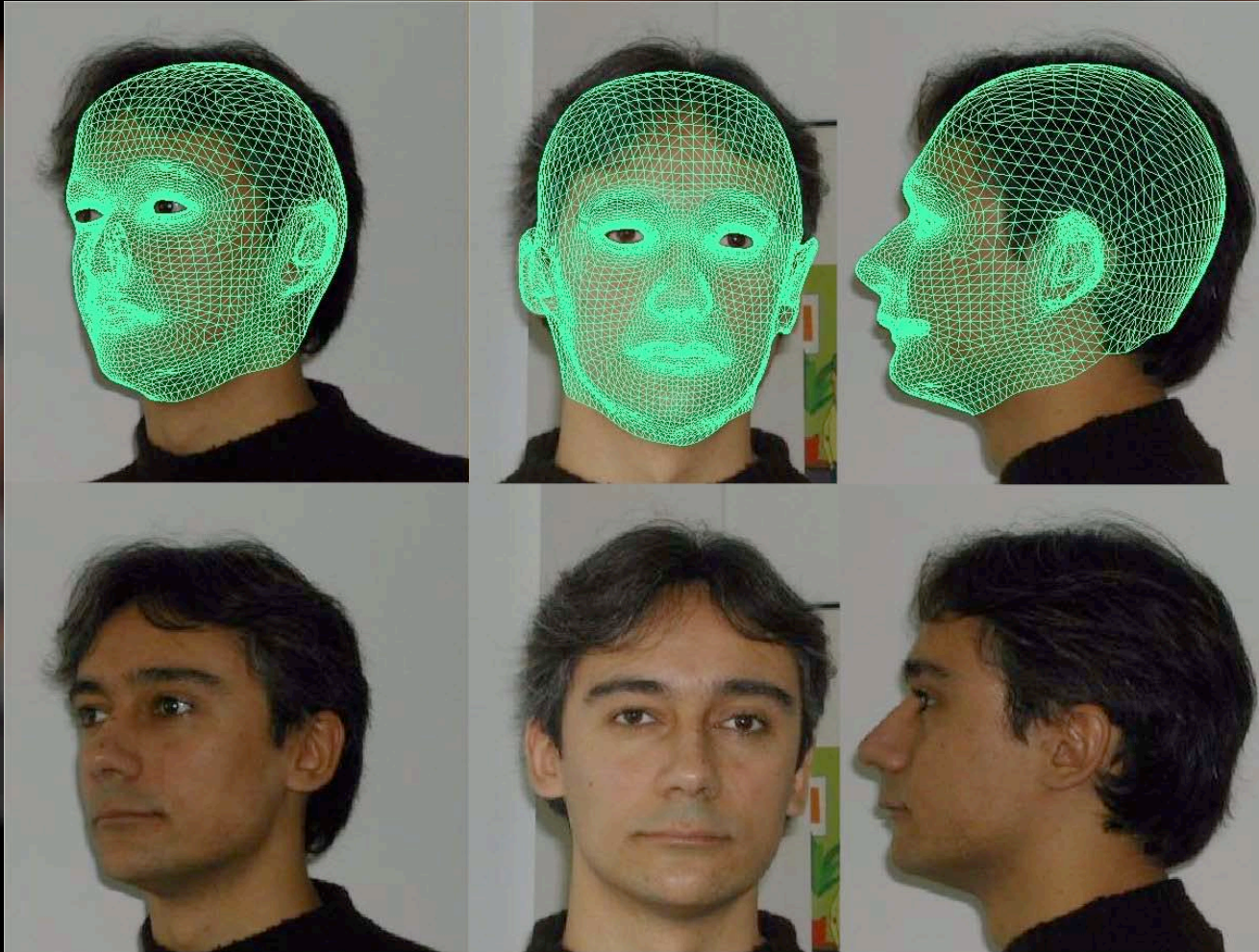
2D \rightarrow 3D Deformations



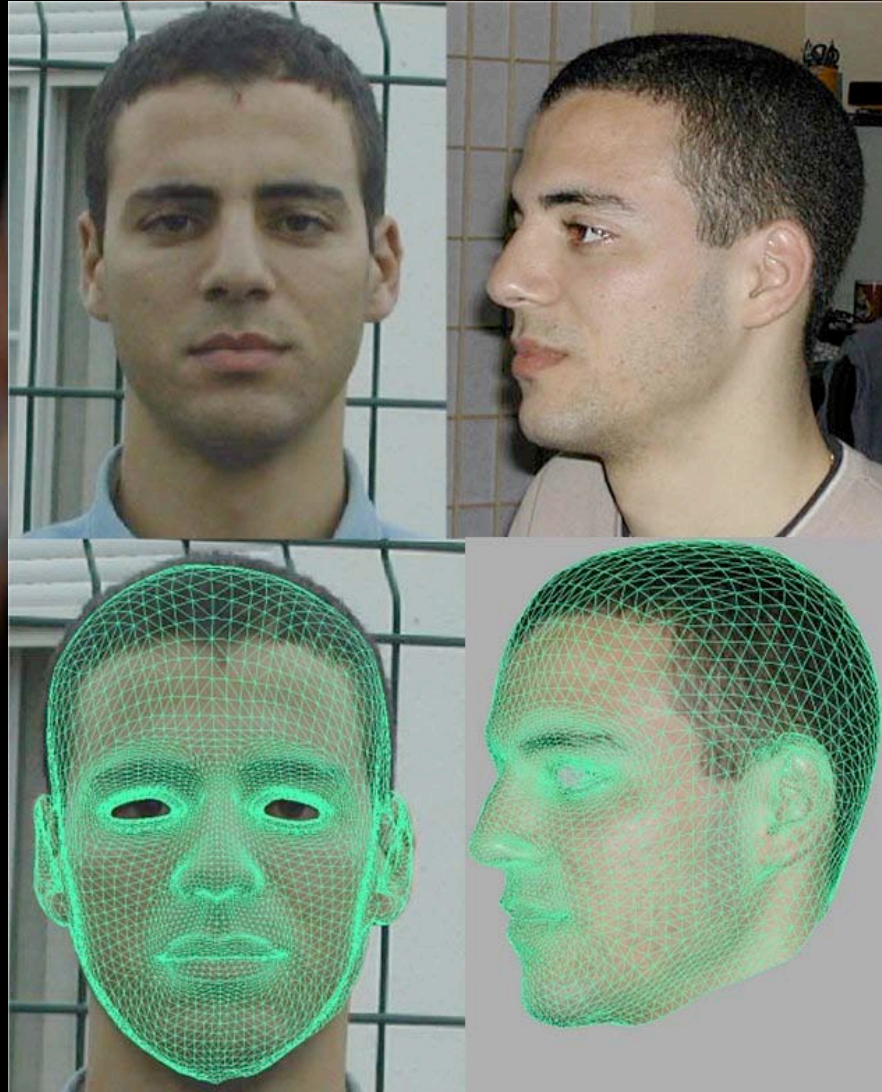


Results

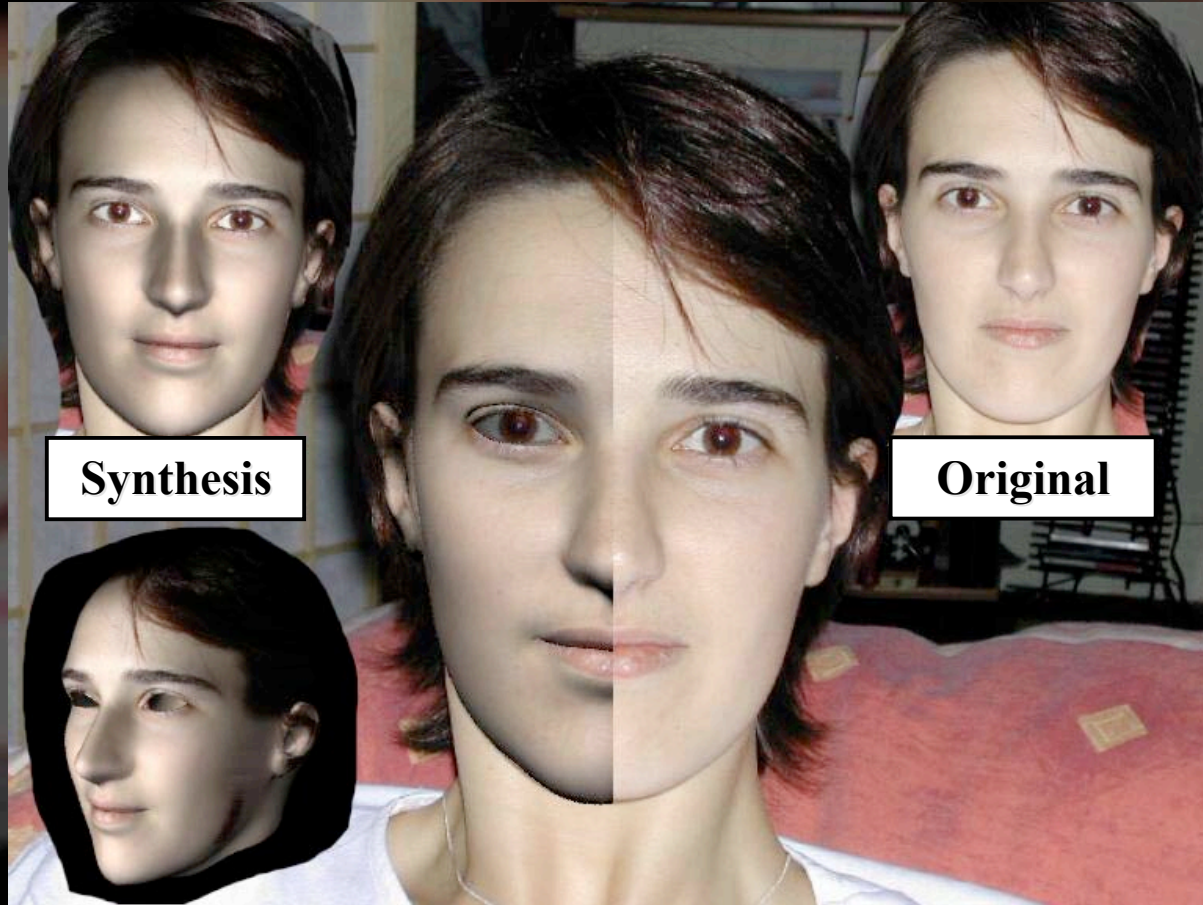
Results



Results



Results

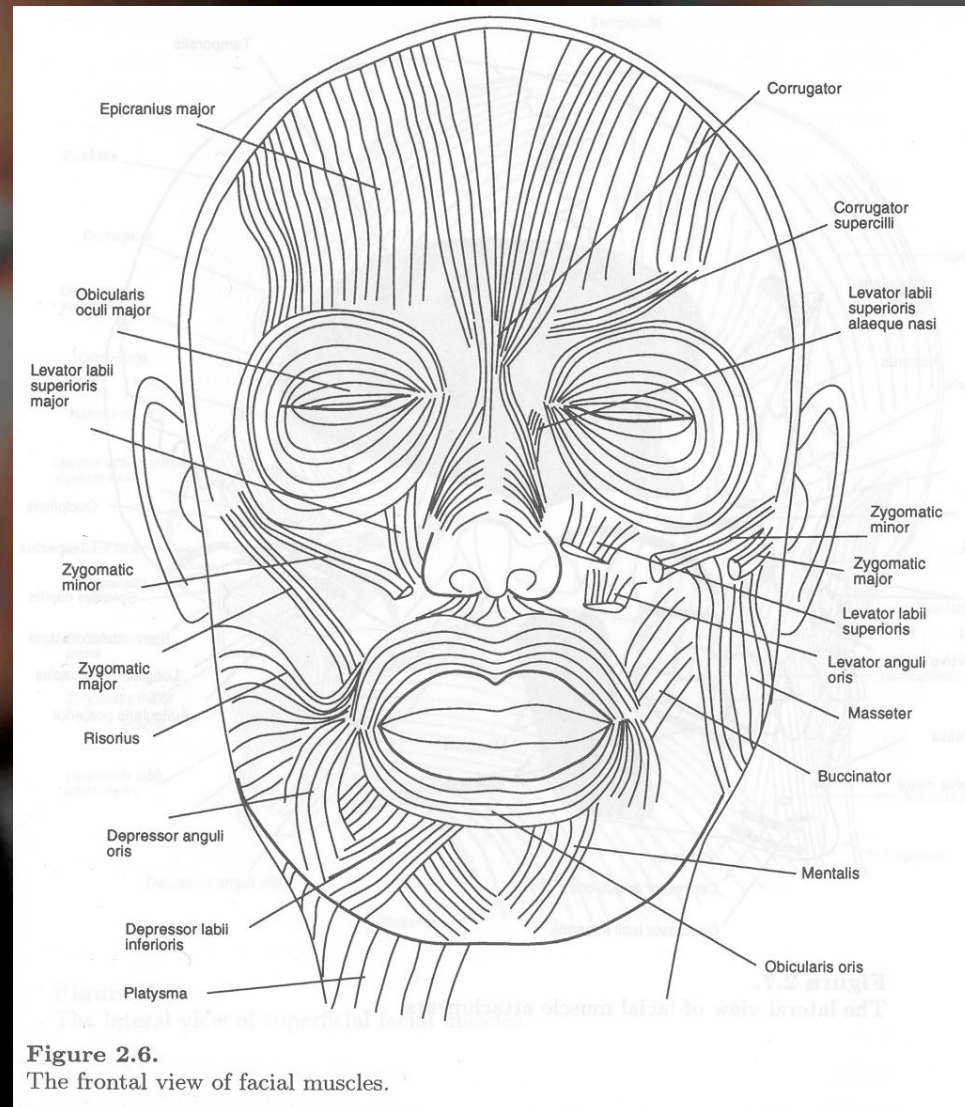




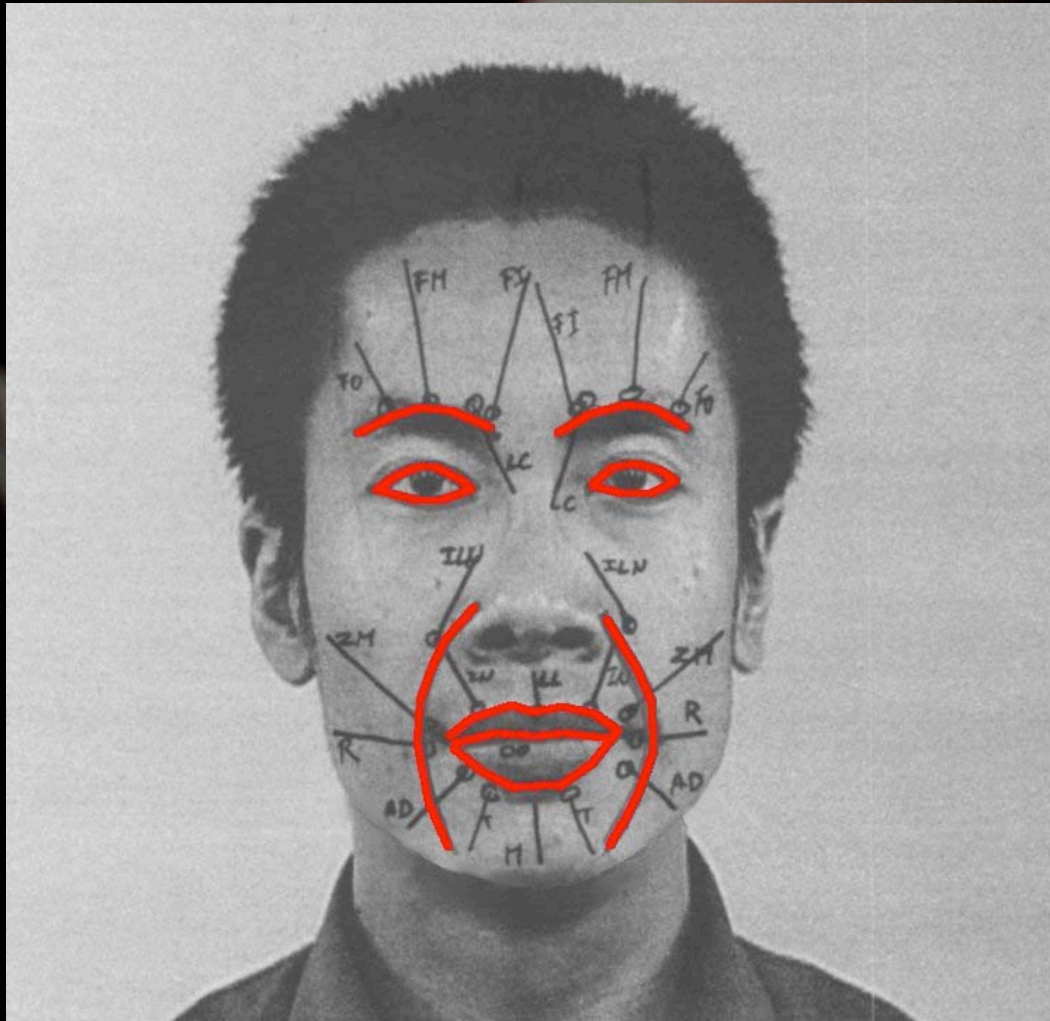
II- Dynamic modelisation of the face's muscles

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Our model is based on study
of muscles that effectively
create expressions on the face



II- Dynamic modelisation of the face's muscles



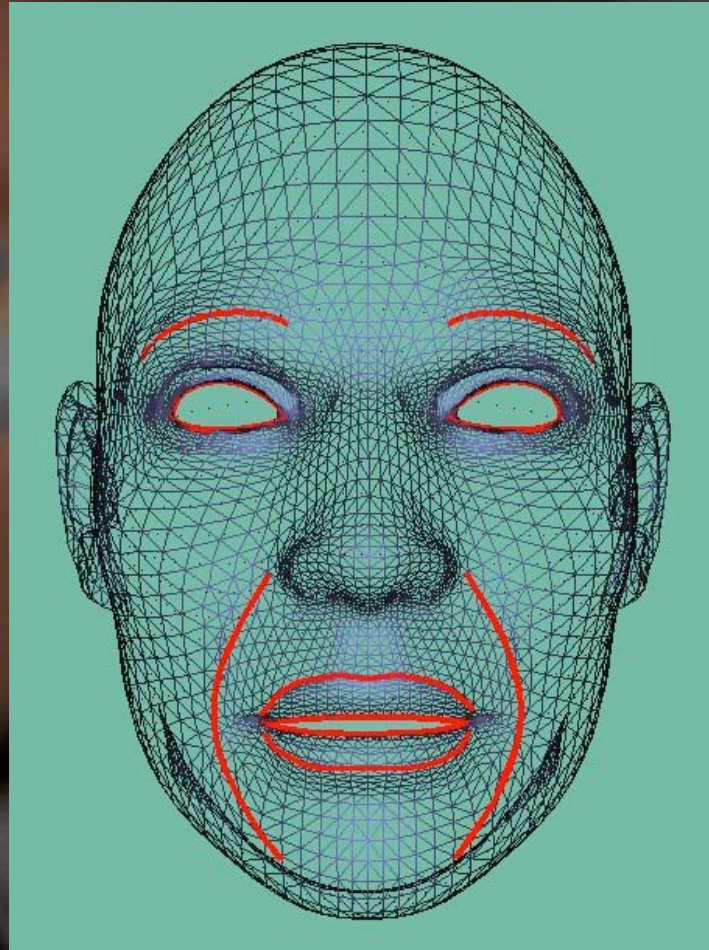
FO : Frontalis outer (x2)	FM: Frontalis Major (x2)
FI: Frontalis Inner (x2)	LC: Lateral Corrugator(x2)
ILN: Inner Labii Nasi(x2)	LL: Levator Labii
LN: Labii Nasi(x2)	ZM: Zygomatic Major(x2)
R: Risorius(x2)	AD: Angular Depressor(x2)
T: Triangularis(x2)	M: Mentalis
OO : Orbicularis Oris(x3)	

Simple idea:

**Deform the curves,
and interpolate the deformations
on the whole face, using RBFs.**

II- Dynamic modelisation of the face's muscles

*Neutral
Generic face
with its
deformation
curves*



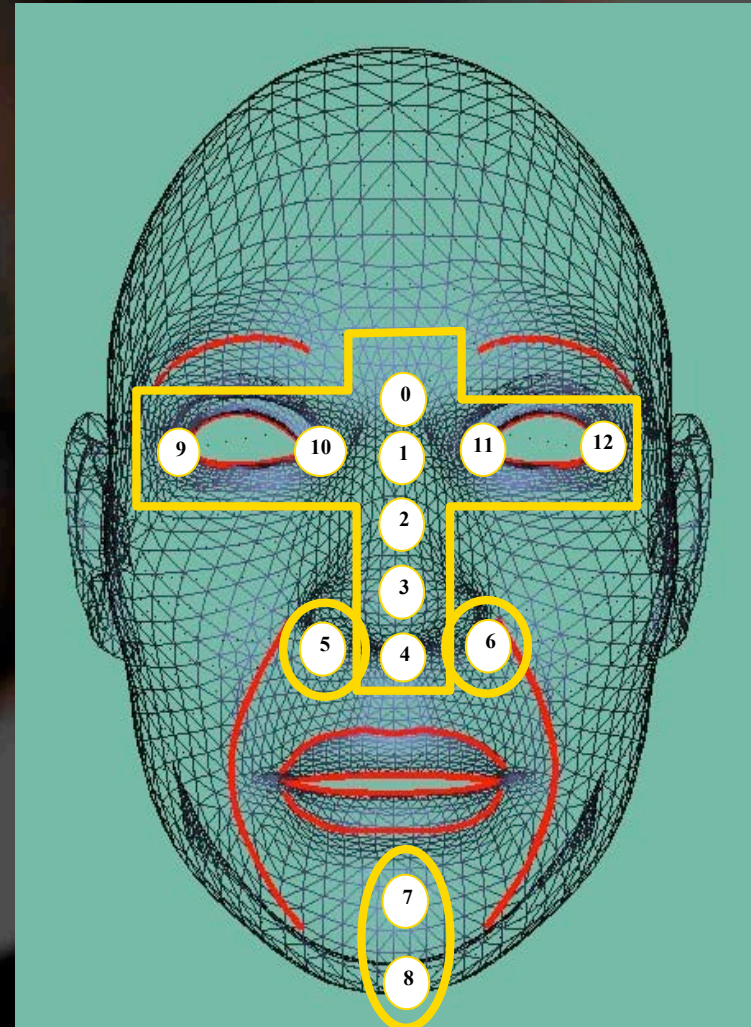
III- Dynamic modelisation of the face's muscles

Static points (force a zero deformation)

- Points on the nose
- Corners of the eyes

Dynamic Points

- On the Chin
- Nostrils



This model is controlled by 15 behaviours:

7 behaviours for the lower part of the face. (mouth and cheeks)

Lower lip height

Upper lip height

Mouth width

Mouth corner height

Lower lip advance

Upper lip advance

Chin

2 behaviors for the eyes.

Right eyelid

Left eyelid

6 behaviours for the upper part of the face. (eyebrows and forehead)

Inner right eyebrow height

Inner left eyebrow height

Central right eyebrow height

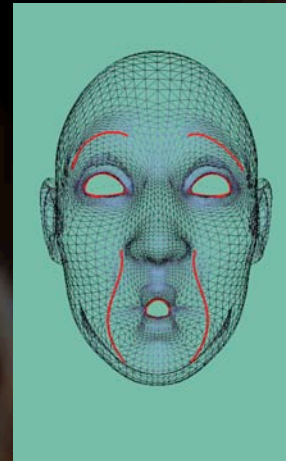
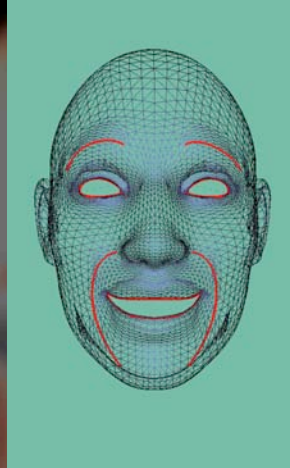
Central left eyebrow height

Outer right eyebrow height

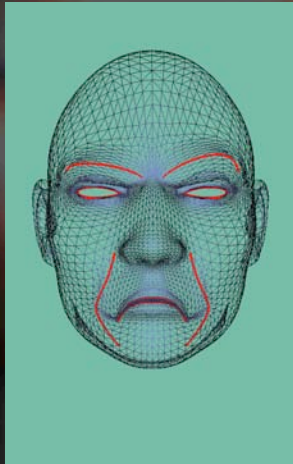
Outer left eyebrow height

Happiness

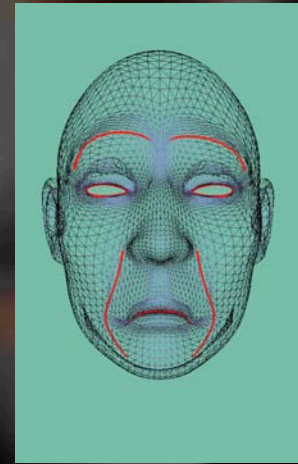
Surprise



Anger



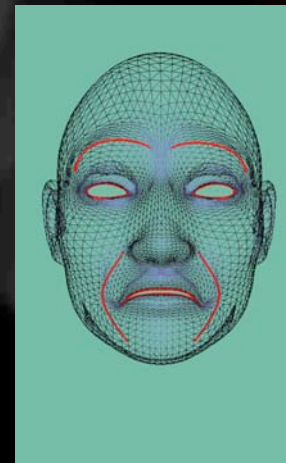
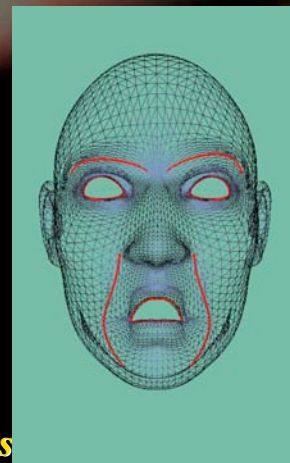
Sadness



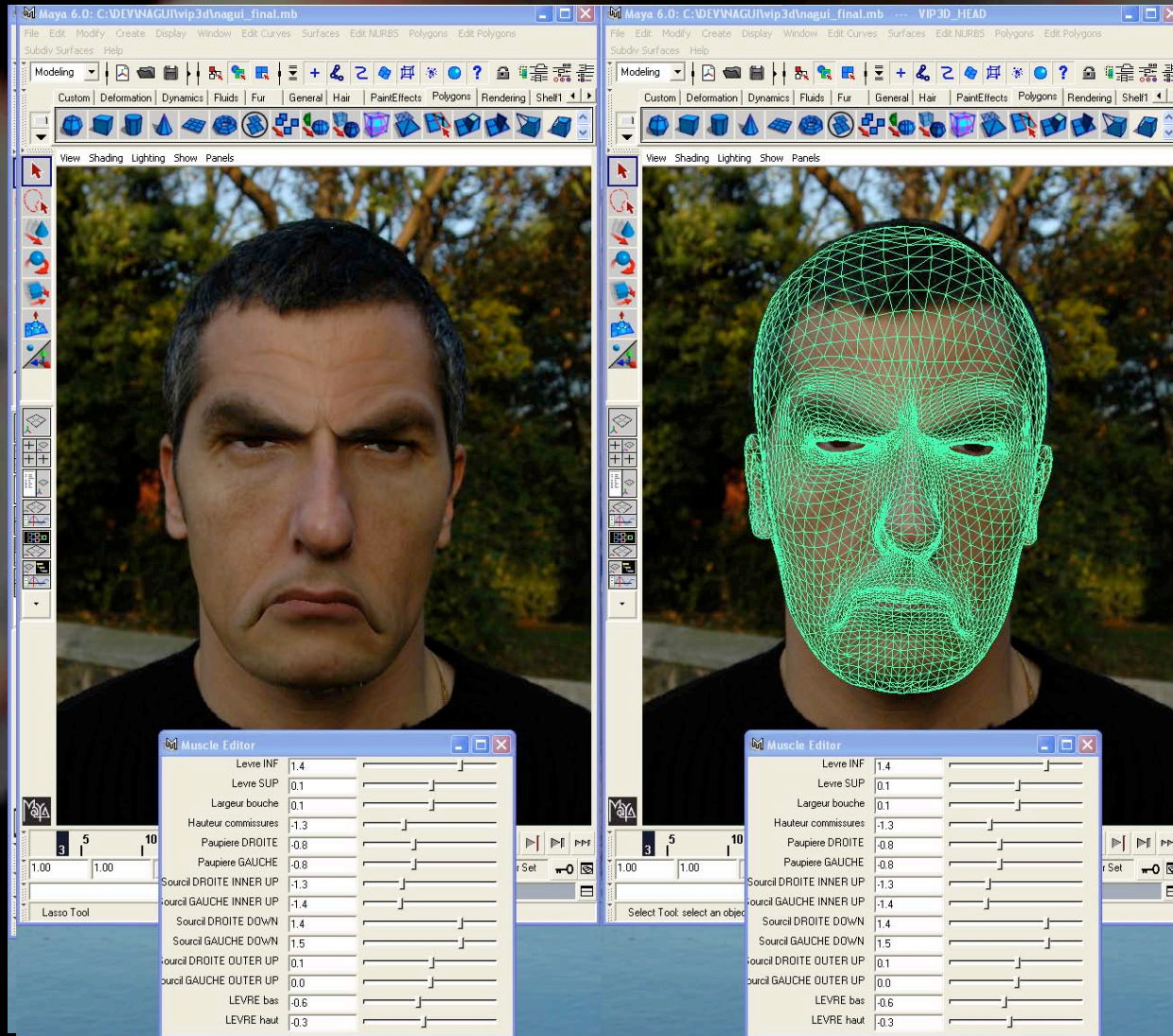
6 universal expressions

Fear

Disgust



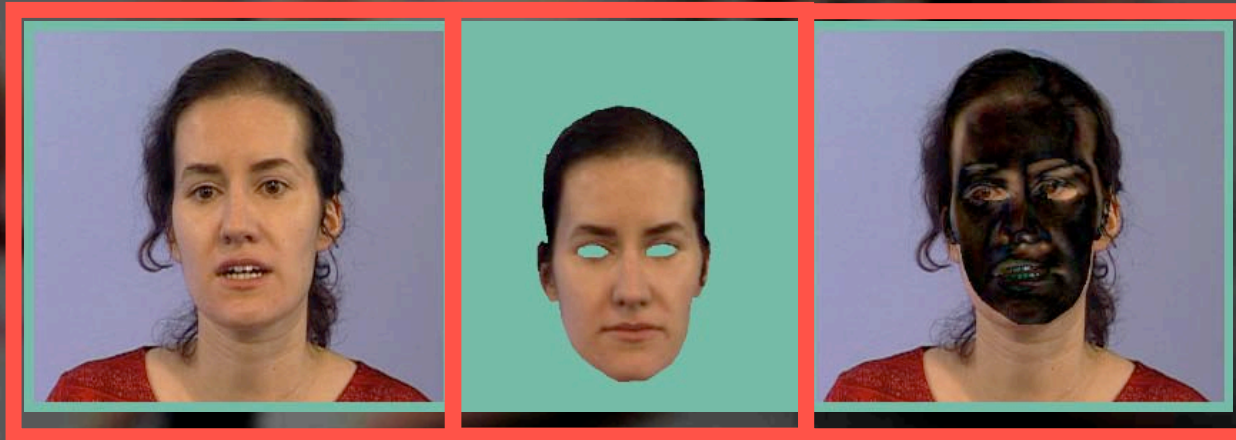
II- Dynamic modelisation of the face's muscles





**III- 3D tracking in image sequence
based on analysis/synthesis loop.**

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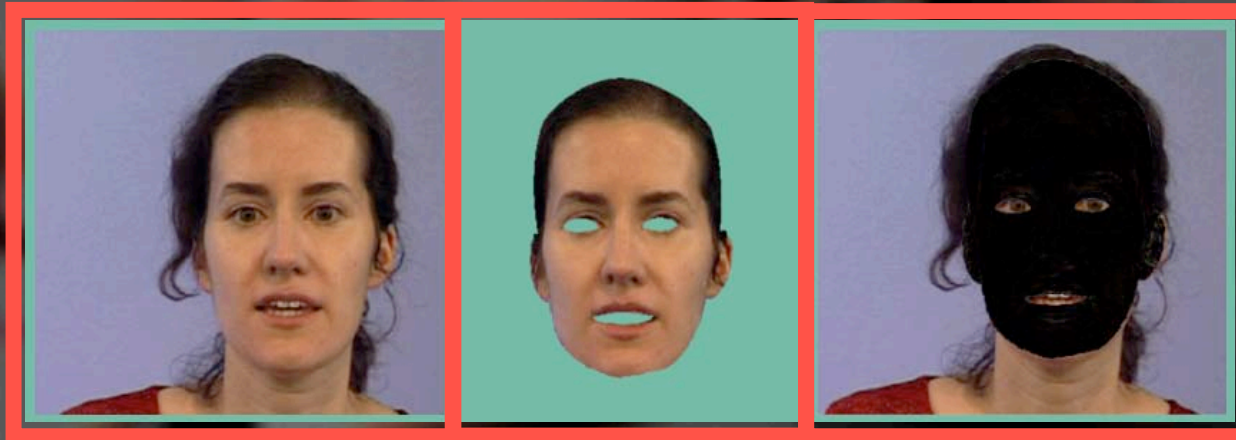


**Image to
compute**

**Textured
3D mesh**

Error

III- 3D tracking in image sequence based on analysis/synthesis loop.

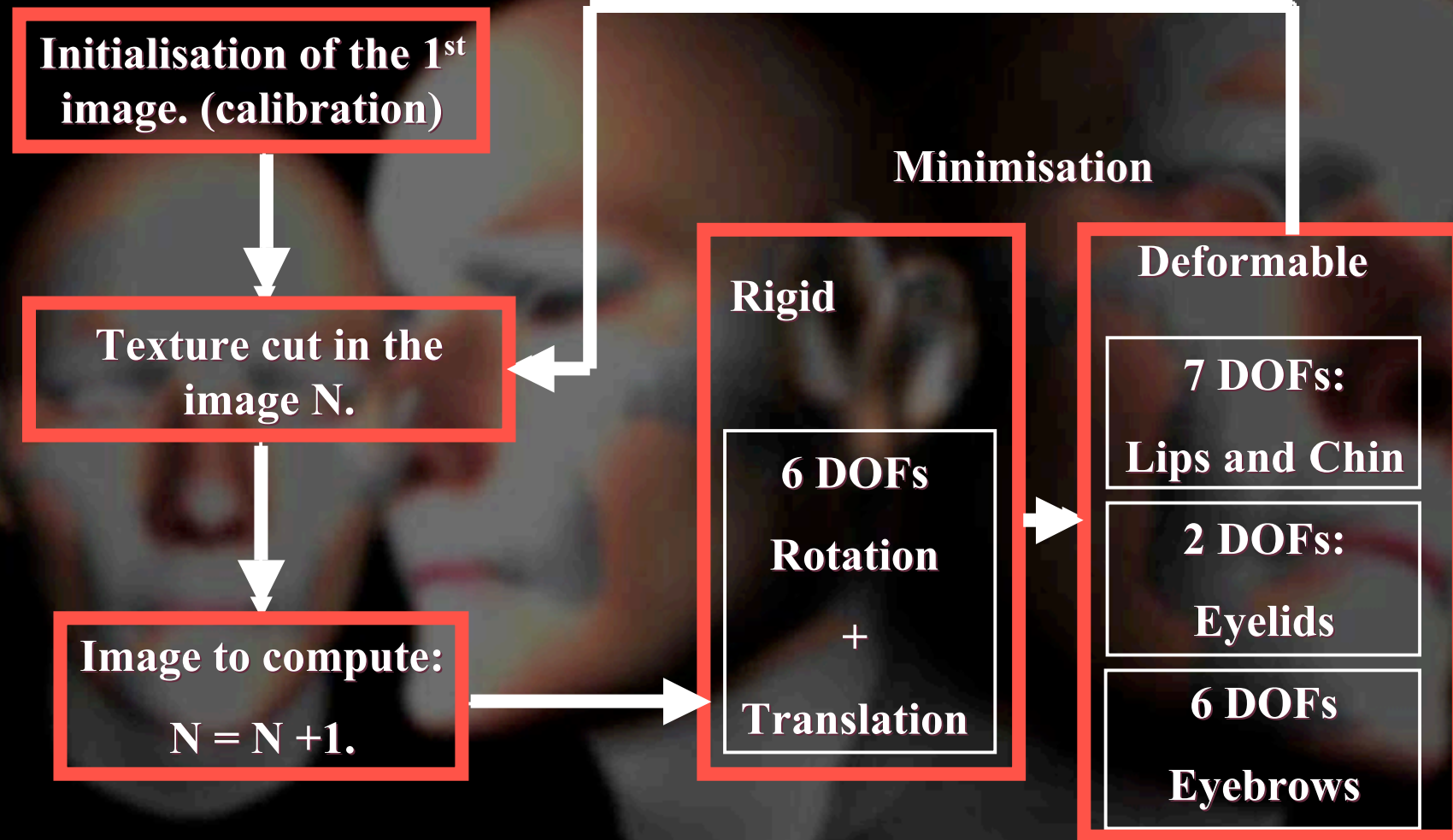


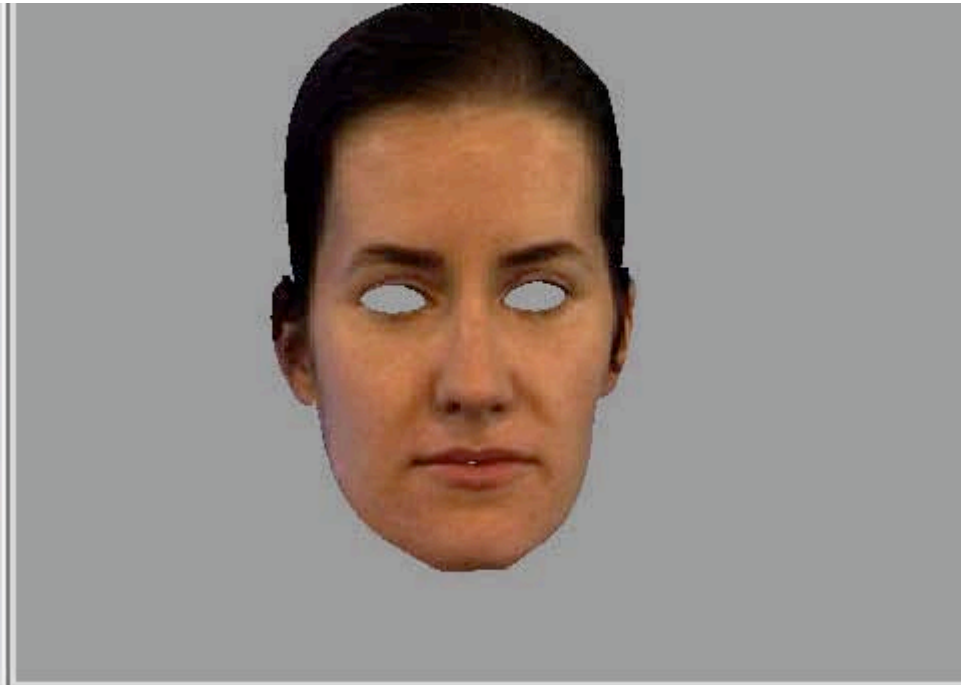
**Image to
compute**

**Textured
3D mesh**

Error

Tracking global scheme

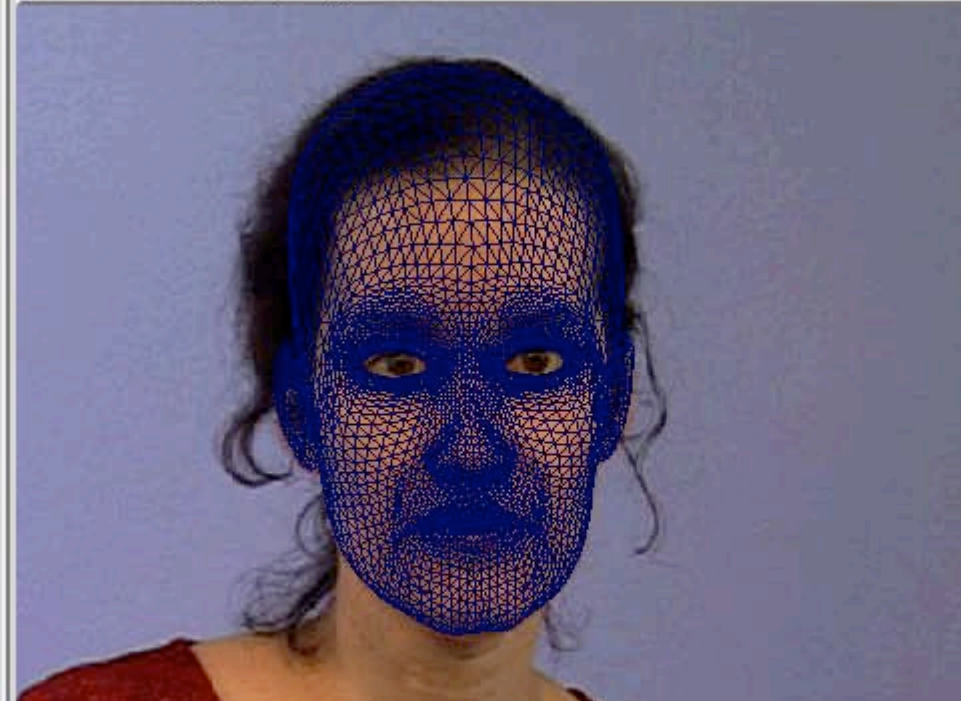


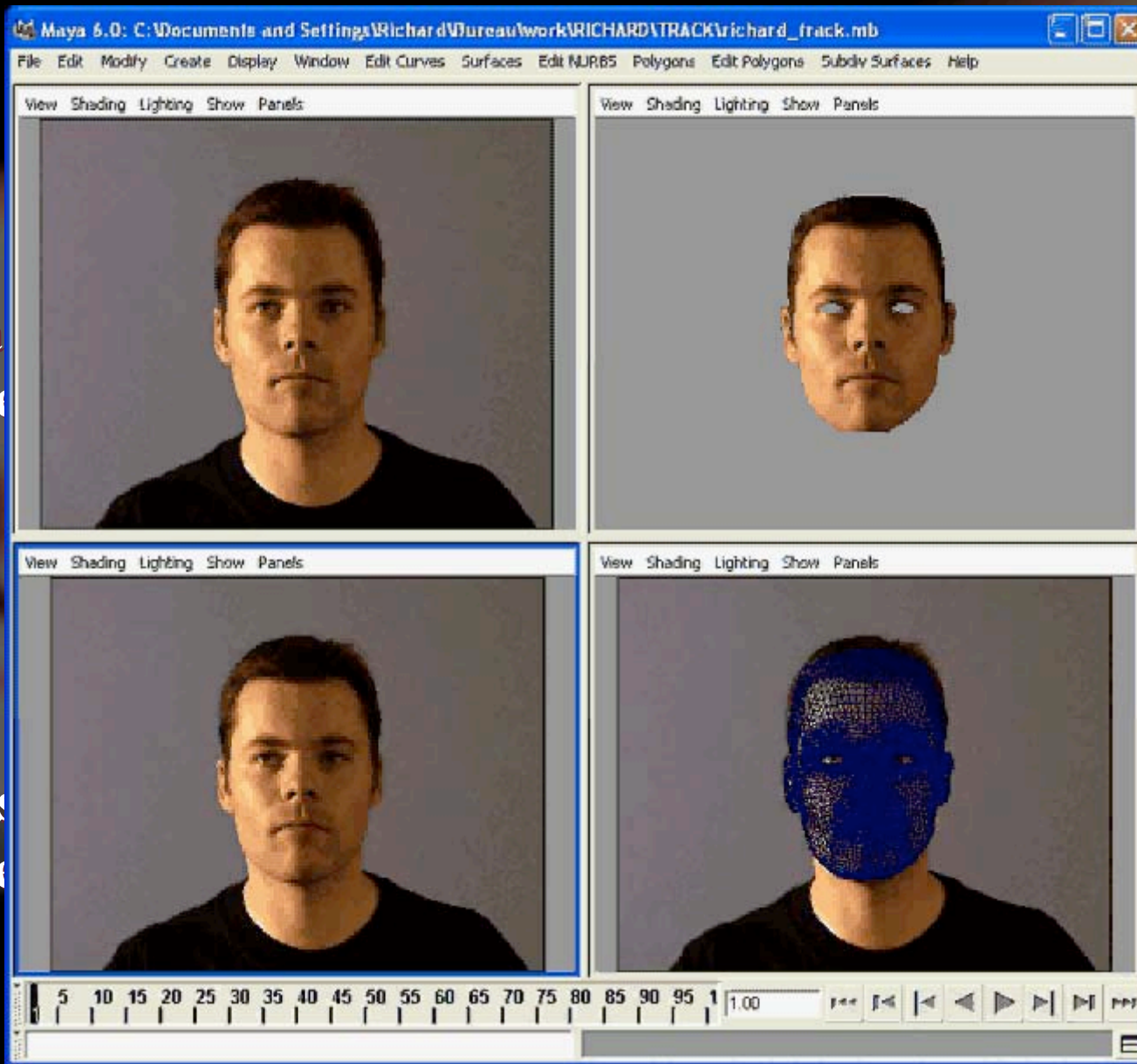


Shading Lighting Show

Panels

View Shading Lighting Show





**Original
image**

**Textured
face**

**Synthesis
image**

3D mesh

Futur works

Speed up tracking, (using GPU...),

Add new behaviors,

Add eyeballs tracking ...



Any question ?